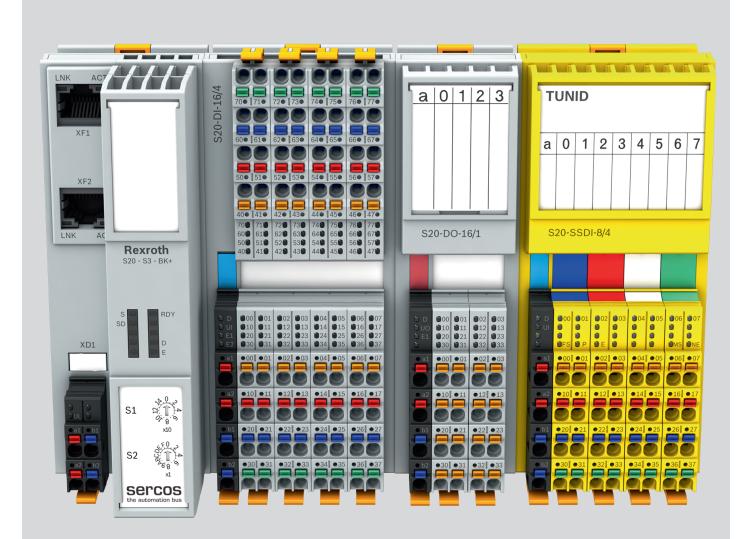


# IndraControl S20 Error Messages

Application Description R911344826 Edition 02



Title	IndraControl S20 Error Messages
Type of Documentation	Application Description
Document Typecode	DOK-CONTRL-S20*DIAG*ER-AP02-EN-P
Internal File Reference	105993_en_01, R911344826_02.pdf
<b>Record of revision</b>	

Edition	Release date	Note
01	2014-06	First edition
02	2021-04	Revision change

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Editorial department Engineering automation systems control hardware

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Use of the safety instructions

# 1 Use of the safety instructions

#### 1.1 Structure of the safety instructions

The safety instructions are structured as follows:

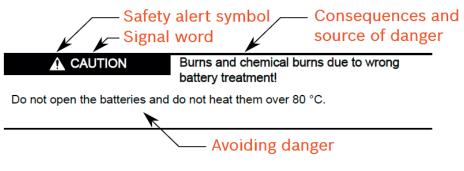


Abb. 1-1 Structure of the safety instructions

### **1.2** Explaining signal words and safety alert symbol

The safety instructions in this documentation contain specific signal words (danger, warning, caution, notice) and, if necessary, a safety alert symbol (according to ANSI Z535.6-2006).

The signal word is used to draw attention to the safety instruction and also provides information on the severity of the hazard.

The safety alert symbol (a triangle with an exclamation point), which precedes the signal words danger, warning and caution is used to alert the reader to personal injury hazards.

#### **DANGER:**

In case of non-compliance with this safety instruction, death or serious injury will occur.

#### WARNING:

In case of non-compliance with this safety instruction, death or serious injury **can** occur.

#### **CAUTION:**

In case of non-compliance with this safety instruction, minor or moderate injury can occur.

#### NOTICE

In case of non-compliance with this safety instruction, material damage can occur.

Use of the safety instructions

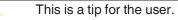
#### Symbols used 1.3

Hints are represented as follows:



This is an information.

Tips are represented as follows:



5/30

Diagnostics in the IndraControl S20 system

# 2 Diagnostics in the IndraControl S20 system

Terms used in the document:

Local bus	IndraControl S20 local bus
Head of an IndraControl S20 station	E.g., IndraControl S20 bus coupler, IndraControl S20 controller
Local bus master	Part of the head of the IndraControl S20 station that is re- sponsible for controlling the IndraControl S20 local bus
IndraControl S20 module	Any module of an IndraControl S20 station, i.e., head of the IndraControl S20 station or I/O module

The IndraControl S20 modules indicate the errors that occur in various ways:

- Via the local diagnostic indicators
- Via diagnostic object 0018<sub>hex</sub> (DiagState)
- Via the diagnostic registers of the bus couplers

### 2.1 Local diagnostic and status indicators

All IndraControl S20 modules are provided with diagnostic and status indicators for quick local error diagnostics. They enable the clear localization of system errors (bus errors) or I/O errors.

**Diagnostics** The diagnostic indicators (red, yellow or green) provide information about the state of the module and, in the event of an error, provide information about the type and location of the error. The module is working correctly when all of its green LEDs are on.

Status The status indicators (yellow) indicate the status of the associated input or output and of the connected I/O device.

**Extended diagnostics** Some modules have extended diagnostics. For example, this enables a short circuit cuit or overload of the sensor supply to be detected and reported. If a short circuit occurs at an output, some output modules can diagnose each channel individually. Information about the supply voltage is also reported. The module sends information about I/O errors to the controller with precise details of the error type. In addition, the status indicators signal the error.



Only the D (diagnostics for local bus communication) and E (error) LEDs are described below.

For an overview of all the main diagnostic and status indicators in the IndraControl S20 system and their meaning, please refer to the DOK-CONTRL-S20\*SYS\*INS-APRS-EN-P, R911335988 application description.

For information regarding the diagnostic and status indicators on a particular module and their meaning, please refer to the module-specific documentation.

#### 2.1.1 D and E indicators on bus couplers

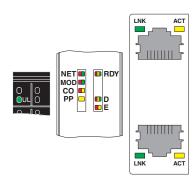


Fig. 2-1

Indicators on bus couplers, example: S20-EIP-BK

Designa- tion	Color	Meaning	State	Description		
D	Red/	Diagnostics for	cs for local bus communication			
	yellow/ green	Run	Green on	The station is ready to operate, communication within the station is OK. All data is valid. A malfunction has not occurred.		
		Active	Flashing green	The station is ready to operate, communication within the station is OK. The data is <b>not</b> valid. The controller or higher-level network is not providing valid data. A malfunction has not occurred on the module.		
			Flashing green/red	A rest system will be operated, at least one device of the configura- tion cannot be reached.		
		Ready	Yellow on	The station is ready to operate. No data is being exchanged.		
		Active +	Flashing yellow	Access via DTM in I/O check mode		
		Force	Flashing yellow/red	Local bus error during active I/O check		
		Ready +	Flashing red	Local bus error during active I/O check		
		Bus error		Possible causes:		
			Configuration cannot be generated, information is miss- ing from a device			
				Chip version of a device is <v1.1< td=""></v1.1<>		
				The desired and actual configuration are different		
		Active +		No local bus device connected		
				Maximum number of local bus devices exceeded		
			Red on	The station is ready to operate, but has lost connection to at least		
		Bus error		one device.		
				Possible causes:		
				Communication error		
				<ul> <li>Local bus device has been removed or a configured de- vice is missing</li> </ul>		
				Reset at a local bus device		
				• Serious device error at a local bus device (local bus device can no longer be reached)		
		Power down	Off	The station is in (power) reset or in energy-saving mode.		
E	Yellow/	Error	Yellow on	I/O warning at a local bus device		
	red		Red on	I/O error at a local bus device		
			Off	No I/O messages present.		

D and E indicators on controllers and bus couplers

#### 2.1.2 Indicators on I/O modules

2.1.2.1 D and E indicators on I/O modules



Fig. 2-3 D and E LEDs on the power connectors of the I/O modules (examples)

Designa- tion	Color	Meaning	State	Description			
D	Red/	Diagnostics for local bus communication					
	yellow/ green	Run	Green on	The device is ready to operate, communication within the station is OK. All data is valid. A malfunction has not occurred.			
				The connection to the controller is present.			
		Active	Flashing green	The device is ready to operate, communication within the station is OK. The data is <b>not</b> valid. The controller or higher-level network is not provid- ing valid data. A malfunction has not occurred on the module.			
		Device applica- tion not active	Flashing green/ yellow	<ul> <li>The device is ready to operate, communication within the station is OK.</li> <li>Output data cannot be output and/or input data cannot be read in.</li> <li>There is a malfunction on the I/O side of the module.</li> <li>The controller is providing valid process data.</li> </ul>			
		Ready	Yellow on	<ul> <li>The device is ready to operate, but has still not detected a valid cycle after power up.</li> <li>There has been no communication since the last power up.</li> </ul>			
		Connected	Flashing yellow 1 Hz	The device is not (yet) part of the active configuration.			
		Reset	Red on	The device is ready to operate, but has lost the connection to the bus head.			
		Not connected	Flashing red	The device is ready to operate, but there is no connection to the previous device.			
		Power down	Off	Device is in (power) reset.			
				The supply voltage is not present.			
				Energy-saving mode is active.			
E1/E2	Red	Error	On	Error, see module-specific documentation.			
			Off	No error.			



D and E LEDs on the power connectors of the I/O modules

# 2.2 Diagnostics via object 0018<sub>hex</sub> (DiagState)

In addition, each I/O module features object  $0018_{hex}$  (DiagState), which is used for the structured reporting of an error. The I/O module also provides its diagnostic state in this way.

The object is illustrated in the module-specific documentation of each I/O module.

Index [hex]	Object name	Data type	Length in bytes	Meaning		
0018	DiagState	Record		Diagnostic state	Complete	diagnostic information
.1	Consecutive no.	UINT16	2	Error num- ber	0 65535 <sub>dec</sub>	Unique, consecutive error number since the last power up or reset of the diagnos- tic counter
.2	Priority	UINT8	1	Priority		he message. 1: Highest priority -8 on page 2-10
					00 <sub>hex</sub>	No malfunction
					01 <sub>hex</sub>	Error
					02 <sub>hex</sub>	Warning
					03 <sub>hex</sub>	Information
					81 <sub>hex</sub>	Error removed
					82 <sub>hex</sub>	Warning removed
					83 <sub>hex</sub>	Information removed
.3	Channel/ Group/ Module	aroup/	1	Channel/ group/ module	Channel, group or module where the malfunction oc- curred.	
					formation".	information available under "Additional in-
					00 <sub>hex</sub>	No malfunction
					xx <sub>hex</sub>	Channel xx, group xx or module xx
					FF <sub>hex</sub>	Entire device
.4	Code	Octet string	2	Error code		
.5	MoreFollows	Bit string 8	1	Additional	Further info	ormation about the malfunction
				information	00 <sub>hex</sub>	Subindex 3 = channel number
					04 <sub>hex</sub>	Subindex 3 = group number
					08 <sub>hex</sub>	Subindex 3 = module number
					Other	Not used at present.
.6	Text	Visible string	Max. 51	Text	Plain text n	nessage. Default: Status OK

Fig. 2-5

Diagnostic state (read) according to basic profile V2.x

Index [hex]	Object name	Data type	Length in bytes	Meaning		
0018	DiagState		23 + max. 100	Diagnostic state	Current dia	agnostic state of the device in short form
.01	Consecutive no.	UINT16	2	Consecu- tive number	0 65535 <sub>dec</sub>	Unique, consecutive error number since the last power up or reset of the diagnos- tic counter
.02	Priority	UINT8	1	Priority		he malfunction. 1: Highest priority ·8 on page 2-10
					00 <sub>hex</sub>	No malfunction
					01 <sub>hex</sub>	Error
					02 <sub>hex</sub>	Warning
					03 <sub>hex</sub>	Information
					81 <sub>hex</sub>	Error removed
					82 <sub>hex</sub>	Warning removed
					83 <sub>hex</sub>	Information removed
.03	Channel	UINT8	1	Channel	Channel or	n which the malfunction occurred.
					00 <sub>hex</sub>	No malfunction
					xx <sub>hex</sub>	Channel xx
					FF <sub>hex</sub>	Entire device
.04	Code	Octet string	2	Error code		
.05	MoreFollows	Bit string 8	1	Additional information	Information Fig. 2-7)	n for interpreting the following data (see
.06	Reserved	Octet string	2	Reserved	(= 0000 <sub>hex</sub>	)
.07	SubModNo	UINT8	1	Submodule number		e is a modular device, the corresponding e is specified here.
					If the devic here.	e is not a modular device, "0" is entered
.08	Function- Group	Octet string	8	Function group	Short desig diagnostics	gnation of the function of the group reporting s.
					For examp	le:
					RTD (0x52 0x00)	0x49, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00) 9, 0x54, 0x44, 0x00, 0x00, 0x00, 0x00, 0x00, 0, IOL, CNT, INC, RS485, PSDI, PSDO, SC
						acturer-specific designation ay OUT") is specified in the diagnostic text 1).



Objects for diagnostics: Diagnostic state (read) according to basic profile V3.x

Index [hex]	Object name	Data type	Length in bytes	Meaning	
.09	AddValue	Octet string	4	Additional information	"Additional value" for the current diagnostic state of the device.
.0A	TextLength	UINT8	1	Text length	Length of the following diagnostic text in bytes.
.0B	Text	Visible string	Max. 100	Diagnostic text	Device-specific explanation of the malfunction that oc- curred.
					Information includes:
					Error type
					Function group and channel
					Terminal point
					Option for action for the user
					Default: "Status OK"
					The string is terminated with 00 <sub>hex</sub> .

Fig. 2-6

Objects for diagnostics: Diagnostic state (read) according to basic profile V3.x [...]

Byte/bit	Value	Meaning			
Byte	00 <sub>hex</sub>	No further information			
Bit 0	1	There is further information about this error. You can read it via object E800 <sub>hex</sub> "DiagStateLong" (if implemented).			
Bits 1 3	0	Reserved			
Bit 4	1	There are additional simultaneously occurring diagnostic events. You can read them via object E806hex "ComplDiagState" (if im- plemented).			
Bits 5 6	0	Reserved			
Bit 7	1	Indication that this is an extended version of object $0018_{hex}$ (compared to version V2.x).			
		E. Additional information			

Fig. 2-7 Index 5: Additional information

Priority	Priority Message type Example		Note	
01 <sub>hex</sub>	High	Error (malfunction, alarm)	Supply voltage faulty Parameter table invalid	A malfunction has occurred that requires a re- sponse. For example, a malfunction requires action in the drive, but does not necessarily require the system to be stopped with immediate effect.
02 <sub>hex</sub>	Medium	Warning	Limit value undershot or ex- ceeded	Risk of an error. A warning does not require action to be taken in the device.
03 <sub>hex</sub>	Low	Information (mes- sage, notification)	General operating message: 10,000 operating hours have elapsed.	General operating message: 10,000 operating hours have elapsed.

Fig. 2-8 Classification of the error messages



Diagnostic object 0018<sub>hex</sub> is implemented with a storage depth of 1. This means that:

- A higher priority message overwrites a lower priority message.
- If a higher priority message is already present, lower priority messages will not be reported.

### 2.3 Diagnostic registers of the local bus master

The errors reported to the local bus master by the I/O modules are mapped to the diagnostic registers of the local bus master.

A local bus master has three diagnostic registers:

- Diagnostic status register:
   Operating and error states of the IndraControl S20 local bus
- Diagnostic parameter register 1: Returns the associated error code in the event of an error
- Diagnostic parameter register 2: Returns the error location for localized bus or I/O errors (device number)

#### 2.3.1 Diagnostic status register

Information on the operating and error states of the IndraControl S20 local bus is stored in the diagnostic status register. An local bus state is assigned to each bit in the diagnostic status register.

The states in the error bits (F\_PW\_BIT, F\_PF\_BIT, F\_BUS\_BIT, F\_CTRL\_BIT) are described in greater detail using the two diagnostic parameter registers.

Bit	Designation	Meaning	
00	F_PW_BIT	I/O warning	At least one device is indicating an I/O warning.
01	F_PF_BIT	I/O error	At least one device is indicating an I/O error.
02	F_BUS_BIT	Bus error	A bus error has occurred.
03	F_CTRL_BIT	Controller error	The driver has detected an internal error.
04	-		Reserved
05	F_RUN_BIT	Run	Data cycles are being exchanged, output data is enabled.
06	F_ACTIVE_BIT	Active	Configuration is active, PDI to the devices is possible, data exchange with invalid/non-enabled process data.
07	F_READY_BIT	Ready	Local bus master is ready to operate, no data exchange via the bus.
08	F_BD_BIT	Bus different	A device which does not belong to the active configuration has been de- tected at the last interface.
09	F_BASP_BIT	SYS_FAIL	The controller is in the STOP state or no application program has been loaded. The output data is blocked (substitute value behavior is active)
10	F_FORCE_BIT	Force mode	Force mode is active.
11	F_SYNC_BIT	Synchronization	Synchronization between higher-level system and local bus master failed.
12	F_PARA_REQ	Module parameter	At least one device is requesting parameters.
1315	-		Reserved

Fig. 2-9 Diagnostic status register

#### Status displays

The Ready, Active, and Run status displays indicate the current state of the system. The diagnostic parameter registers are not used.

Following initialization, the driver is ready to operate. The Ready indicator bit is set  $(F\_READY\_BIT = 1)$ .

If the driver has been configured and a configuration frame has been activated without errors, the system indicates that it is active. The Ready and Active indicator bits are set ( $F_READY_BIT = 1$ ,  $F_ACTIVE_BIT = 1$ ).

In addition, the Run indicator bit is set ( $F_READY_BIT = 1$ ,  $F_ACTIVE_BIT = 1$ , and  $F_RUN_BIT = 1$ ) when data exchange is started.

#### **Error indicators**

The PF, BUS, CTRL, and SYNC error indicators report an error, while PW reports a warning.

Errors which are indicated with BUS or CTRL will cause the bus to be disconnected. The Run indicator bit is reset ( $F_RUN_BIT = 0$ ).

Further information on the error cause is provided by the two diagnostic parameter registers.

If several error bits are 1 at the same time, the values in the parameter registers represent the error with the highest priority.

Priority
1 (highest priority)
2
3
4
5 (lowest priority)

Fig. 2-10 Priorities of the error messages

If there are I/O errors (PF= peripheral fault) at several devices, the parameter registers show the message that occurred first. When you remove this message, the next pending massage with the lowest device number is shown.

If there are I/O warnings (PW = peripheral warning) from several devices, the warnings are shown in the same way as the I/O errors.

After an error has been removed or disappears (e.g., elimination of an interruption), the bus is started again automatically and the output data is enabled again. The Run indicator bit is set again ( $F_RUN_BIT = 1$ ).

#### 2.3.2 Diagnostic parameter registers

The diagnostic parameter registers are always written to when a malfunction occurs and whenever one of the error bits (F\_PW\_BIT, F\_PF\_BIT, F\_BUS\_BIT, F\_CTRL\_BIT) is set. Otherwise, the diagnostic parameter registers have the value  $0000_{hex}$ .

When the aforementioned error bits are set, the diagnostic parameter registers provide additional information on the status indicated in the diagnostic status register.

Diagnostic parameter register 1 contains the error code. For an overview of the error codes, please refer to Section 3, "Error codes".

Diagnostic parameter register 2 contains additional information. For localized bus or I/O errors, this is the error location or the device number. The error location is stored as a slot number. This starts at 1 and corresponds to the sequential number of the IndraControl S20 modules that are installed one after another.

# 2.4 Diagnostic registers of the bus couplers

The diagnostic registers of the local bus master can be read via the diagnostic mechanisms of the higher-level system (see Fig. 2-11).

Bus coupler	Higher-level system	Diagnostic mechanism	See	Web-based management
S20-PB-BK	PROFIBUS	Diagnostics in common format, block 6, bytes 9 12	DOK-CONTRL- S20*PB*BK**-APRS-EN-P, R911343914	No
S20-EC-BK	EtherCAT®	CoE object F100 <sub>hex</sub> : Bus Coupler Diag Info	DOK-CONTRL- S20*EC*BK**-DARS-EN-P, R911372200	No
S20-PN-BK	PROFINET	Diagnostic alarms	DOK-CONTRL- S20*PN*BK+*-DARS-EN-P, R911342784	Yes
S20-ETH-BK	Ethernet	Modbus registers: Local bus diagnostics: 7997 diagnostic status register 7998 diagnostic status register 1 7999 diagnostic status register 2 I/O diagnostics: 1801 1989 I/O diagnostics of the local bus devices	DOK-CONTRL- S20*ETH*BK*-DARS-EN-P, R911372205	Yes
S20-EIP-BK	EtherNet/IP™	Diagnostic object (class code 67 <sub>hex</sub> )	DOK-CONTRL- S20*EIP*BK*-APRS-EN-P, R911377106	Yes
S20-S3-BK+	Sercos	Diagnostic IDNs	DOK-CONTRL- S20*S3*BK+*-DARS-EN-P, R911342782	No

Fig. 2-11 Diagnostic mechanisms of higher-level systems



Further options for diagnostics:

For devices with web-based management:
Open the "Diagnostics" menu item. You can call the diagnostics for the bus coupler and local bus here.

Problems when invoking the firmware services or problems during operation are reported with error codes to determine the exact cause of the error. The following sections explain the meaning of the individual codes.

The code listed in the tables consists of the error class and error code. The Additional Code parameter contains a more detailed description of the error cause.

### 3.1 Error codes for user errors

Code (hex)	Additional code	Meaning	Remedy	
0903		Memory problem (e.g., buffer too small)	Reduce the amount of data.	
0904		Inconsistent parameters.	Check the parameters.	
0905		Invalid parameters.	Check the parameters.	
0908	Code of failed service	Maximum number of permitted parallel services exceeded. (Processing conflict)	Wait for the previously invoked service to be completed and try again.	
090A	Value transmitted in Parameter_Count	The number of parameters is inconsistent with the service. The Parameter_Count parameter does not match the number of subsequent words.	Adjust the number of parame- ters.	
0913	Code of failed service	The invoked service is not supported.	Use a service that is supported.	
0917	Code of failed service	Service decoding failed.	Restart the device. If the problem persists, please contact Bosch Rexroth.	
0918	Code of the unknown service	Invocation of an unknown service code.	Check the invocation.	
0928		An exclusive service was to be executed without the appropriate rights.	Wait for the exclusive rights to be enabled.	
0932		Attempt to pass on the exclusive rights without having these rights.		
0933		Another node currently has the exclusive rights.	Wait for the exclusive rights to be enabled.	
0934		Node already has the exclusive rights.		
0937	Invalid Variable_ID	Unknown variable ID component.	Check the invocation.	
0938	Reserved Variable_ID	An internal variable ID was used.	Check the invocation.	
0939	Variable_ID not en- abled	The variable ID is not enabled. (Password protection)	Check the invocation.	
093A	Incorrect Variable_ID	Length specification in the variable ID is 0 or incorrect.	Check the invocation.	
093B	Incorrect Vari- able_Count	The number of variables has been calculated incorrectly.	Check the invocation.	

Fig. 3-1 Error codes for user errors

Code (hex)	Additional code	Meaning	Remedy
0A01		A hardware fault or firmware error has occurred.	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A02	Current state of the local bus master	A service was invoked that is not permitted in the current status of the local bus master.	Set the local bus master to the re- quired state.
		Possible states:         0001       Ready (After restart or reset)         0002       Load config (Configuration cannot be loaded)         0004       Config ready (Configuration loaded successfully)         0008       Active (Configuration frame connected)         0010       Param ready (Parameterization of modules completed)         0020       Run (Process data traffic running)         0080       Force mode (Startup tool specifies outputs)         0100       Ready fail (Communication breakdown in Ready)         0800       Active fail (Communication breakdown in Active)         1000       Param ready fail (Communication breakdown in Param Ready)         2000       Run fail (Application timeout for all devices)         8000       Force Mode Fail (Communication breakdown in force mode)	
0A03		Memory problem (e.g., buffer too small)	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A04		Inconsistent parameters.	Check the invocation.
0A05		Invalid parameters.	Check the invocation.
0A06		Access not supported.	Check the invocation.
0A07		Object does not exist.	Check the invocation.
0A08	Code of failed service	Maximum number of permitted parallel SM services exceeded. (Processing conflict)	Wait for the previously invoked service to be completed and try again.
0A0C	Unknown Variable_ID	Invocation of Set_Value or Read_Value with a Vari- able_ID that contains an unknown code.	Check the invocation.
0A0D		A firmware error occurred.	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A0E	Current state of the local bus master	Energy-saving mode cannot be activated in the current state of the local bus master.	Set the local bus master to the re- quired state.

Fig. 3-1 Error codes for user errors [...]

Code (hex)	Additional code	Meaning	Remedy
0A18	Invalid Used_Attri- butes parameter	A reserved bit is set in Used_Attributes.	Check the parameters.
0A19	Number of bus devices	The end of the frame was exceeded when accessing the configuration or line 0 was accessed.	Check access.
0A1A	Invalid Frame_Refer- ence (if specified)	The frame reference specified for the service does not exist.	Check the parameters.
0A1C	Number of connected devices	Maximum number of devices exceeded.	Reduce the bus configuration.
0A2F		Number of devices is zero.	Connect the device and check the connection.
0A51		Only a frame reference from 1 to 254 is permitted.	Only the value 1 is permitted at present.
0A54		The maximum number of permissible I/O points was exceeded.	Reduce the number of I/O points to the maximum number.
			For the exact number, please refer to the documentation for your controller.
0A60		A configuration frame could not be assigned.	Create the configuration frame.
0A70		A reserved bit is set in the Diag Info attribute.	Check the parameters.
0A73	Device number	Device with an unsupported chip version present in the local bus.	Replace the device.
0A74	Device number	Device from an unsupported manufacturer present in the local bus.	Replace the device.
0A75	Device number	Device is reporting a serious error (e.g., faulty EE- PROM).	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A76	Device number	The master does not support the topology used by the device.	Replace the device.
0A77	Device number	Error at the interface.	Check the connection between the electronics module and bus base module.
0A79	Device number	The device requires parameters for correct operation.	Parameterize the device or re- start it.
0A7A		Invalid Dev_Type specified during loading.	Check the parameters.
0A7B		Invalid Dev_ID specified during loading.	Check the parameters.
0A7C		Invalid Dev_Length specified during loading.	Check the parameters.
0A81	Object index	Service (e.g., Create_Configuration) could not be exe- cuted due to PDI communication malfunctions (timeout).	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A82	Object index	Service (e.g., Create_Configuration) could not be exe- cuted due to PDI communication malfunctions (num- ber).	Restart the device. If the problem persists, please contact Bosch Rexroth.

Fig. 3-1 Error codes for user errors [...]

Code (hex)	Additional code	Meaning	Remedy
0A83	Object index	Service (e.g., Create_Configuration) could not be exe- cuted due to PDI communication malfunctions (error).	Restart the device. If the problem persists, please contact Bosch Rexroth.
0A90	Device number	Device was selected for synchronization, but does not support this.	Select a device that supports synchronization or change the selection.
0A91	Device number	Device was selected for synchronization, but does not support the specified cycle time.	Select a different cycle time or a different device.
0A92	Device number	Device was selected for synchronization, but does not support the specified value for Input_Delay.	Select a different value for In- put_Delay or a different device.
0A93	Device number	Device was selected for synchronization, but does not support the specified value for Output_Delay.	Select a different value for Out- put_Delay or a different device.
0A94	Device number	Device was selected for synchronization, but does not support the specified values for Input_Delay and Out-put_Delay.	Select different values for In- put_Delay and Output_Delay or a different device.
0AFF		Invocation of Reset_Driver during PDI communication.	Restart the device. If the problem persists, please contact Bosch Rexroth.
0B01		A hardware fault or firmware error has occurred.	Restart the device. If the problem
0B02		A hardware fault or firmware error has occurred.	persists, please contact Bosch Rexroth
0B03		A hardware fault or firmware error has occurred.	
0B04		A hardware fault or firmware error has occurred.	
0B05		Invalid parameters.	Check the parameters.
0B06		Access not supported. (E.g., write protection)	Restart the device. If the problem
0B07		Object does not exist.	persists, please contact Bosch Rexroth.
0B0C		A hardware fault or firmware error has occurred.	
0BC1		Supply voltage for the local bus not present. Too many	Use a suitable power supply unit.
		devices connected or the higher-level power supply unit is too weak.	Check the current consumption of the devices. If necessary, use a power module or set up an- other IndraControl S20 station.
0BC2		The local bus is in energy-saving mode. The supply voltage has been switched off.	Deactivate energy-saving mode.
0BDE		Synchronization failed. Trigger signal does not corre- spond to the specification.	Check the synchronization signal of the higher-level system. Make sure that you have selected the cycle time specification correctly.

Error codes for user errors [...]

#### Error codes for bus diagnostics 3.2

Code (hex)	Additional code	Meaning	Remedy
0BD1		The bus could not be activated successfully due to malfunc-	Check the bus configuration.
0BF1		tions on the bus.	
0BF2			
0BF3			
0C01	Device number	The configured module cannot be reached.	Check the configuration.
		A device present in the configuration frame has been re- moved from the physical bus structure after the configuration frame was connected.	Adapt the configuration frame if the change was made on purpose.
0C02		An unconfigured module has been detected.	
		An additional device was added at the end of the physical bus structure after the configuration frame was connected.	
0C11		The module is not located in the configured slot.	
		An active device was placed elsewhere in the physical bus structure after the configuration frame was connected.	
0C12	-	The module can be reached, but was not started up due to missing parameters.	
		An active device was replaced by an unknown device in the physical bus structure after the configuration frame was connected (wrong instance ID).	
0C13		The process data length does not correspond to the config- ured value.	
		The process data width of an active device was changed after the configuration frame was connected.	
0C14	1	The module type does not correspond to the configured	
0C15		value.	
0C16		An address conflict has occurred.	Restart the station.

Fig. 3-2 Error codes for bus diagnostics

# 3.3 Error codes when invoking the PDI services

In Fig. 3-3, the additional code is only specified if it contains a special value. The standard values for the additional code are listed in Fig. 3-4.

The code consists of the error code and error class.

Example:

 $Code = 0501_{hex}$ : Error class =  $05_{hex}$ , Error code =  $01_{hex}$ 

Code (hex)	Additional code	Meaning	Remedy
02xx		Error in the communication relationship	Check the invocation.
0200		Miscellaneous error	
0201		Unable to access the object.	
		<ul><li>Possible causes:</li><li>Module not present</li><li>Incorrect module number</li></ul>	
05xx		Invalid service	Check the invocation.
0500		Miscellaneous error	
0501		The current object state is preventing the service from being executed.	
0502		Problem with the PDU size	
-		Permissible length exceeded. Object cannot be read in full.	
0503		The service cannot be executed at present.	
0504		The service contains inconsistent parameters.	
0505		A parameter has an impermissible value.	
06xx		Invalid access	Check the invocation.
0600		Miscellaneous error	
0601		Invalid object	
0602		Hardware fault	Eliminate the hardware fault (e.g., I/O volt- age not present).
			Restart the device. If the problem persists, please contact Bosch Rexroth.
0603		Access to object denied, insufficient access rights	Check the invocation.
0604		Access to an invalid internal address	
0605		Inconsistent object attributes	
0606		The service used cannot be applied to this object.	
0607		Object does not exist	
0608		The data does not correspond to the data type of the object.	
060A		The object data cannot be accessed at present (e.g., during reparameterization).	

Fig. 3-3 Error codes when invoking the PDI services

**21/**30

Code	Additional	Meaning	Remedy
(hex)	code		
08xx		Error in the application	
0800		The service was not executed. The reason is specific to the application or manufacturer and only affects the actual data item. Refer to the additional code for the precise reason.	
		Example: A certain object value is not permitted in this special ap- plication.	
	xx30	A reserved bit or reserved code was used during param- eterization. xx: Number of the affected element 30: Value is out of range	Check the parameterization.
0801		The service was not executed. The reason is specific to the device. Refer to the additional code for the precise reason.	
080B		The service cannot be completed by the device in the expected time.	
		The estimated time still required for the data to become available is given in ms in the additional code. "0xFFFF" means that the estimated time for completion is unknown.	
0F01		Hardware fault or firmware error	Restart the device. If the problem persists,
0F02			please contact Bosch Rexroth.
0F03			
0F04		Inconsistent parameters.	Check the parameters.
0F05	PDI object index	Invalid parameters.	Check the parameters.
0F06	PDI object index	Access not supported.	Check the invocation.
0F08	PDI object index	Maximum number of permitted parallel PDI services exceeded.	Wait until the services have been pro- cessed.
0F0C	Unknown Variable_ID	Incorrect variable ID for Set_Value or Read_Value.	Check the invocation.
0F0D		Internal error	Restart the device. If the problem persists,
0F11		Internal error	please contact Bosch Rexroth.
0F12		Device cannot be reached (timeout).	Check the device.
0F13		Device cannot be reached because it was removed.	Check the bus configuration.
0F21	Invalid device num- ber	Invalid slot number. (Value is 0 or greater than the maximum number of de- vices)	Check the invocation.
0F22	Invalid device num- ber	Slot is not active.	Check the invocation.

Error codes when invoking the PDI services [...]

Code (hex)	Additional code	Meaning	Remedy
0F23	Invalid data length	Invalid data length.	Check the invocation.
0F24	Invalid num- ber of parameters	Invalid number of parameters.	Check the invocation.
0F31		Internal error	Restart the device. If the problem persists,
0F32			please contact Bosch Rexroth.
0F33			

Fig. 3-3

Error codes when invoking the PDI services [...]

0000	No detailed information on the cause of the error.
0010	Service parameter with impermissible value.
0011	Subindex is not present.
0012	Object access is not a request.
0013	Service code is not supported.
0014	Subslot is not supported.
0015	Object access type is not supported on this object.
0016	Object access request index for this AccessType must equal 000 <sub>hex</sub> .
0017	Object access request length for this AccessType must equal 0.
0018	Object length is not suitable for this object.
0019	Object is ReadOnly and cannot be overwritten.
001A	Object is WriteOnly and cannot be read.
001B	Write/read access to the object is not supported.
001C	Due to the object length, Upload Read or Download Write is required for access to the object.
001D	Object length is not suitable for this object (0018). Too much data was transmitted.
001E	Object length is not suitable for this object (0018). Too little data was transmitted.
0020	Service cannot be executed at present.
0021	Service cannot be executed at present, as the device is currently being controlled locally.
0022	Service cannot be executed in current device state (device control).
0023	Service cannot be executed at present, as no object dictionary is available.
0024	Index is not available.
0030	Parameter value is out of range.
0031	Parameter value is too large.
0032	Parameter value is too small.
0040	Collision with other values, dependency was not taken into consideration.
0041	Communication object cannot be mapped to the process data.
0042	Process data length exceeded.

Fig. 3-4 Additional codes

Additional code (hex)	Meaning
0050	<ul> <li>Firmware update: General.</li> <li>Firmware is incorrect for the device</li> <li>Device unable to process firmware</li> </ul>
0051	<ul> <li>Firmware update:</li> <li>Due to the object length, Upload Read or Download Write is required for access to the object.</li> <li>Incorrect firmware header or update version.</li> </ul>
0052	<ul><li>Firmware update: Firmware version is incorrect for the device.</li><li>Below minimum firmware version (e.g., hardware is too old)</li></ul>
0053	Firmware update: Indicates the option to bypass the download of a FW update block to the device.
0080	Hardware fault
0081	Application has failed.
0082	Hardware is temporarily faulty.
00A0	Invalid segment number, e.g., upload without initiation with subindex ==FF <sub>hex</sub> .
00A1	Resource not available. No more resources (memory) available for download.
00A2	Incorrect CRC (checksum)
00A3	Error opening the file (if file system is available).
00A4	Error writing the file (if file system is available).
00A5	Error closing the file (if file system is available).
00A6	Segment missing: Fewer data blocks were received than specified in the last segment.
00A7	Extra segment: More data blocks were received than specified in the last segment.
00A8	Error reading the file (if file system is available).
00A9	Invalid segment number (segment duplicated, segment ignored).
00B1	The password cannot be replaced (deleted).
00B2	The password cannot be added (too many passwords).
00B3	The password cannot be assigned for the desired type of access.
Fig. 3-4	Additional codes []

Fig. 3-4 Additional codes [...]

# 3.4 Error codes of the I/O modules

If an error occurs on an I/O module, the module reports this error to the local bus master.

R

Please refer to the module-specific data sheets for the error types that a module reports.

o malfunction eneral malfunction urrent Short circuit Overload of the analog output or short circuit Input overload Overload of the sensor supply for the inputs Overload or short circuit of the sensor supply Overload or short circuit of the actuator supply Overload or short circuit (L+) Output overload Short circuit or overload of an output Overload or short circuit (C/Q cable) Sensor supply overload	Check the wiring.
urrent         Short circuit         Overload of the analog output or short circuit         Input overload         Overload of the sensor supply for the inputs         Overload or short circuit of the sensor supply         Overload or short circuit of the actuator supply         Overload or short circuit (L+)         Output overload         Short circuit or overload of an output         Overload or short circuit (C/Q cable)         Sensor supply overload	Check the wiring.
Short circuitOverload of the analog output or short circuitInput overloadOverload of the sensor supply for the inputsOverload or short circuit of the sensor supplyOverload or short circuit of the actuator supplyOverload or short circuit (L+)Output overloadShort circuit or overload of an outputOverload or short circuit (C/Q cable)Sensor supply overload	Check the wiring.
Overload of the analog output or short circuitInput overloadOverload of the sensor supply for the inputsOverload or short circuit of the sensor supplyOverload or short circuit of the actuator supplyOverload or short circuit (L+)Output overloadShort circuit or overload of an outputOverload or short circuit (C/Q cable)Sensor supply overload	Check the wiring.
Input overloadOverload of the sensor supply for the inputsOverload or short circuit of the sensor supplyOverload or short circuit of the actuator supplyOverload or short circuit (L+)Output overloadShort circuit or overload of an outputOverload or short circuit (C/Q cable)Sensor supply overload	
Overload of the sensor supply for the inputsOverload or short circuit of the sensor supplyOverload or short circuit of the actuator supplyOverload or short circuit (L+)Output overloadShort circuit or overload of an outputOverload or short circuit (C/Q cable)Sensor supply overload	
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Output overload Short circuit or overload of an output Overload or short circuit (C/Q cable) Sensor supply overload	
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Overload or short circuit (C/Q cable) Sensor supply overload	
Sensor supply overload	
bltage	
<b>3</b> -	
Overvoltage at a signal input of the incremental encoder	Check the wiring.
Undervoltage at a signal input of the incremental encoder	Check the wiring.
Output voltage	Check the wiring.
Short circuit or overload at the output	
I/O supply voltage failure	Check the supply.
Overvoltage at port x	
Undervoltage at port x	
Sensor supply not present	
I/O supply voltage failure	
Actuator supply not present	
emperature	
Overtemperature	<ul> <li>Reduce the temperature, for example:</li> <li>Reduce the ambient temperature</li> <li>Ensure sufficient ventilation</li> <li>Reduce the load</li> <li>Check the mounting position</li> </ul>
er	Overvoltage at port x Undervoltage at port x Sensor supply not present I/O supply voltage failure Actuator supply not present mperature

Fig. 3-5 Error codes of the I/O modules

Code (hex)	Meaning	Remedy	
5000	Device hardware		
5112	Faulty 24 V supply	Check the supply.	
	Short circuit or overload at the 24 V supply		
	24 V encoder supply for channel x faulty		
5113	Short circuit or overload at the 5 V supply		
5120	Cold junction invalid	Check the cold junction.	
5160	Supply voltage faulty	Check the supply.	
	I/O supply overload		
6000	Device software		
6300	Parameter record incorrect	Check the parameterization of the specified device.	
6301	Device error	Restart the device. Replace the device if the error persists.	
6302	Device error		
6310	Device error: Lost parameters	Parameterize the specified device. Restart the device. Replace the device if the error persists.	
6320	Parameter table invalid	Check the parameterization of the specified device.	
7000	Additional modules		
7300	Encoder error	Check the encoder.	
7305	Encoder error		
7330	Electrical encoder error		
7340	Logical encoder error		
7610	Receive buffer full	Read the receive buffer.	
7611	Transmit buffer full	Check the handshake.	
7620	EPROM (device error)	Restart the device. Replace the device if the error per- sists.	
7710	Wire break on cable to sensor	Remove the wire break.	
	Wire break		
	Wire break on signal line		
8000	Monitoring		
8152	Transmit buffer full	Check the handshake.	
815A	Receive buffer full	Read the receive buffer.	
8600	Incremental encoder input error	<ul><li>Check the input signal.</li><li>Remove the short circuit.</li><li>Connect the encoder.</li></ul>	
8910	Measuring range violated (overrange)	Adjust the range.	
8920	Measuring range violated (underrange)	Check the wiring.	

Fig. 3-5

Error codes of the I/O modules [...]

Code (hex)	Meaning	Remedy	
A000	Modular devices, lower-level bus (sub-bus)		
A001	Lower-level bus: No module present	Check the connected lower-level bus and its power supply.	
	No module found at a port configured as IO-Link (after 5 seconds following port configuration)	<ul> <li>Check whether the IO-Link device is connected correctly.</li> <li>Check the cabling.</li> <li>Replace the IO-Link device.</li> </ul>	
A002	Lower-level bus: Incorrect module present	• Check the specified device and its power	
	Connected IO-Link device does not match IO-Link port configuration.	<ul><li>supply.</li><li>Check the desired and actual configuration.</li></ul>	
A003	Lower-level bus: Module replaced with compatible one		
A004	Lower-level bus: More modules than expected		
A005	Lower-level bus: Residual system operated		
A010	Lower-level bus: Module error		
	Device at the port reporting an event		
A012	Lower-level bus: Application on the module not ready		
A013	Lower-level bus: Device reset		
A014	Lower-level bus: Parameterization error on the de- vice	Check the parameterization.	
	Parameterization error on the device at the rele- vant port. Data storage problem.		
A020	Lower-level bus: Communication error with device	<ul> <li>Check the specified device in the lower-level bus or in the system section for the following aspects:</li> <li>Missing or incorrect shielding of the bus line</li> </ul>	
	Communication error at the relevant port with the connected device.		
A021	Lower-level bus: Timeout	(connector)	
A022	Lower-level bus: Multiple transmission errors	<ul> <li>Missing or incorrect grounding, missing or incorrect equipotential bonding</li> <li>Faulty connections in the connector</li> <li>Voltage dips on the power supply</li> </ul>	
A023	Lower-level bus: I/O data communication error		
A024	Lower-level bus: Management data communica- tion error	Check the specified device and its power supply.	
A030	Lower-level bus: Configuration error	Check the parameterization of the specified device.	
A041	Lower-level bus: Hardware fault	Restart the device. Replace the device if the error per- sists.	
A042	Lower-level bus: Firmware error	Check the parameterization of the specified device.	
A043	Lower-level bus is asynchronous to the higher- level system		

Fig. 3-5

Error codes of the I/O modules [...]

# 4 Service and support

Our worldwide service network provides an optimized and efficient support. Our experts offer you advice and assistance should you have any queries. You can contact us **24/7**.

**Service Germany** Our technology-oriented Competence Center in Lohr, Germany, is responsible for all your service-related queries for electric drive and controls.

Contact the Service Hotline and Service Helpdesk under:

Phone:	+49 9352 40 5060
Fax:	+49 9352 18 4941
E-mail:	service.svc@boschrexroth.de
Internet:	http://www.boschrexroth.com

Additional information on service, repair (e.g. delivery addresses) and training can be found on our internet sites.

Service worldwide Outside Germany, please contact your local service office first. For hotline numbers, refer to the sales office addresses on the internet.

# **Preparing information** To be able to help you more quickly and efficiently, please have the following information ready:

- Detailed description of malfunction and circumstances
- Type plate specifications of the affected products, in particular type codes and serial numbers
- Your contact data (phone and fax number as well as your e-mail address)

Service and support

Notes

The Drive & Control Company



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